

```
(b / break-01
  :ARG0 (k / Kim)
  :ARG1 (v / vase)
  :manner (g / gleefully))
```

Figure 1: A DRS and an AMR for the sentence “Kim broke the vase gleefully”

multilingually and cross-lingually (Kondratyuk and Straka, 2019; Samardžić et al., 2022). UD corpora (manually or automatically annotated) have been used for psycholinguistic and cross-linguistic corpus research, e.g., on word order (Futrell et al., 2015; Guzmán Naranjo and Becker, 2018; Levshina, 2019). But since UD only provides morphosyntactic relations, it is less well suited for similar corpus linguistic research on semantic phenomena, or for NLP tasks such as relation extraction and dialogue systems.

Given the advantages of semantic roles, one would think that SRL tools for many languages should be as readily available as UD parsers. However, this is not currently the case. None of the software libraries mentioned above comes with the capability to predict semantic roles. Freely available SRL systems are usually research prototypes and come with pre-trained models only for a single or few languages and domains (e.g., He et al., 2017; Strubell et al., 2018; Larionov et al., 2019). To a large part this gap is due to the lack of a language-independent annotation standard for semantic roles, comparable to the UD annotation guidelines for syntax. In Section 2, we review existing schemas for semantic role annotation and point out limitations that hamper their widespread adoption. We argue that bottlenecks stem mainly from either lack of frames or too many and fine-grained frames, and from restrictions of schemas to specific morphosyntactic word classes. We present a scheme that addresses these issues in Section 3, report on annotation experiments in Section 4, and conclude in Section 5.

## 2. Limitations of Existing SRL Annotation Schemes

**Large frame inventories** Most schemas define semantic roles via *frames*: A predicate is labeled as evoking a frame such as `break-01`, which defines frame-specific roles such as `ARG0` (breaker) and `ARG1` (thing broken). Some schemas have rather

large and fine-grained inventories of frames. For example, PropBank has 10 687, SynSemClass has 1 993 (Urešová et al., 2022; Urešová et al., 2025), FrameNet has 1 224 (Baker et al., 1998), and VerbAtlas, 466 (Di Fabio et al., 2019). This creates a practical problem in annotation: for each predicate instance, annotators have to find the most appropriate frame, which is non-trivial, and fine-grained distinctions mean that the probability of disagreement is high. It may also be that an appropriate frame does not exist yet and has to be created. Frame lexicons mitigate this problem by creating explicit mappings from lexemes to frames. However, such lexicons are still forever incomplete, and they are language-specific. For a new language, a new lexicon has to be created, or annotators have to translate predicates, which introduces additional ambiguity and disagreement. There are ways to annotate non-English corpora with PropBank frames and roles automatically (Akbik et al., 2015; Jindal et al., 2022), but this also introduces errors.

### Focus on specific morphosyntactic word classes

In annotation, it is important to determine whether and when an annotation is complete. In UD, a syntactic annotation is complete when the dependency edges form a tree over the words of the sentence. A comprehensive semantic role annotation should label the semantic function of every argument and modifier edge between content words. Existing schemas, however, have a tendency to focus on a specific subset of natural-language predicates and their arguments and to some extent modifiers, typically by morphosyntactic word class. VerbNet (Kipper Schuler, 2005) and VerbAtlas (Di Fabio et al., 2019) focus on English verbs; so did PropBank, initially, although support for other words such as nouns and adjectives was later added (Pradhan et al., 2022). FrameNet focused on “nouns, adjectives, and verbs” (Baker et al., 1998) from the start. Modifier relations can be considered to evoke a frame on their own that is not necessarily evoked by a content word (although it is often associated with an adposition or conjunction). PropBank and AMR define different inventories of modifier relations that are separate from the inventory of frames for verbs and other frame-evoking content words. There are also schemas that specialize in other relations that sometimes coincide with modifier relations, such as adposition senses (Schneider et al., 2018), discourse relations (Carlson et al., 2003; Prasad et al., 2008), or compound relations (Tratz and Hovy, 2010; Pepper, 2022). FrameNet and SynSemClass comprehensively address arguments and modifiers of all content word classes, but there is no single *compact* set of frames that does this. As a result, treatment of predicates of different word classes and

```

(o / own-01
 :ARG0 (k / Kim)
 :ARG1 (h / house))

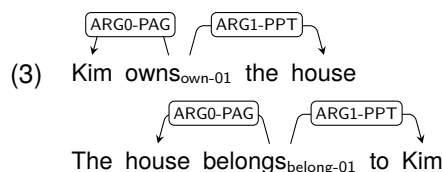
(h / house
 :poss (k / Kim))

```

Figure 2: AMR annotations of the phrases *Kim owns the house* and *Kim’s house*

especially between arguments and modifiers remains somewhat incoherent in many existing annotation frameworks. To illustrate this point, consider the phrases *Kim owns the house* and *Kim’s house*. Both evoke a similar frame, namely a possessor-possessum relationship between Kim and a house. Now consider their AMR annotations in Figure 2. The similarity of the situations denoted is lost in this representation because the verb *own* and the possessive modifier draw from different inventories of labels.

**Lack of precise definitions for roles** Considering the problems with large numbers of frames discussed above, one might be tempted to do away with frames entirely and label each argument (and modifier) in isolation, according to a small set of role labels, each defined in some way. This approach is taken by schemas such as LIRICS (Petukhova and Bunt, 2008, used with some modifications in the PMB) or WISer (Feng et al., 2023). In addition, several schemas do use some notion of frame, but attempt to give meaningful and frame-independent names to roles that are supposed to enable annotators to determine the correct role for each argument even without reference to the frames. Examples of this are VerbAtlas, the tectogrammatical level of the Prague Dependency Treebank (Hajič et al., 2024), and the “functions” decorating PropBank’s frame-specific numbered argument roles. However, it is very hard to clearly define roles without reference to frames, because what makes different arguments of one predicate distinct from each other is their relation to each other. To illustrate this point, consider the sentences *Kim owns the house* and *The house belongs to Kim*. Both evoke a similar frame, namely a possessor-possessum relationship between Kim and a house. Now consider their PropBank annotations (showing both numbered argument roles and “functions”) in (3).



In the first annotation, Kim is PAG (prototypical agent) and the house is PPT (prototypical patient)

whereas in the second, it is the other way around. The similarity between the situations described is missed. Moreover, it is not clear how annotators could determine that these are the correct role labels without looking them up in the frame inventory, or in a language-independent way.

### 3. The Superframes Annotation Scheme

#### 3.1. Design Principles

Superframes was developed to enable rapid, consistent annotation with semantic roles the way UD does for syntactic relations. To this end, Superframes is designed with the following key features:

**(1) Small number of frames** There are only a few dozen frames, shown in Table 1, all binary and indicating coarse semantic relations between two concrete or abstract entities. In annotation, predicates are sorted into these coarse semantic classes, similar to the sorting of word senses into coarse “supersenses” by Ciaranita and Altun (2006); Schneider et al. (2018). For annotation consistency, frames are kept as few and general as possible, but as many and specific as necessary to provide intuitive labels for each argument. For example, while the predicates *own* and *include* both have two arguments, the relation between both arguments in each case is different enough to warrant separate frames: POSSESSION with roles possesum and possessor, and PART-WHOLE with role part and whole, respectively.

**(2) Frame composition** Predicates with more than two arguments are annotated by composing two or more frames. For example, *include* with a causativ subject *include* evokes an additional CAUSATION frame where the core PART-WHOLE frame fills the result role.

**(3) Aspect decomposition** Frames denoting state changes are derived from frames denoting the corresponding states. For example, while *own* evokes POSSESSION, *buy* evokes POSSESSION-INIT.

**(4) Unified frame inventory** The same inventory of frames is used to annotate arguments of all classes of content words, and all modifiers.

**(5) Constrained granularity** Superframes is annotated atop Universal Dependencies. Content words receive frame labels, and the edges connecting them receive argument or modifier labels. In addition, secondary edges for nonlocal dependencies arising from coordination, control, raising,

SUPERFRAME	initial-arg2	arg1	arg2	transitory-arg2	target-arg2
🔗 SITUATION	initial-situator	theme	situator	transitory-situator	target-situator
👤 ACCOMPANIMENT	initial-accompanier	accompanied	accompanier		target-accompanier
👉 L DEPICTIVE		has-depictive	depictive		
👉 L ASSET		has-asset	asset		
👉 L ATTRIBUTE		has-attribute	attribute		
👉 L COMPARISON		compared	reference		
👉 L CONCESSION		asserted	conceded		
👉 L EVENT		undergoer	event		
👉 L ACTIVITY		is-active	activity		
👉 L EXISTENCE	initial-exists	material	exists		target-exists
👉 L REPRODUCTION		original			copy
👉 L TRANSFORMATION-CREATION		material			created
👉 L EXPERIENCE		experiencer	experienced		
👉 L EXPLANATION		explained	explanation		
👉 L PURPOSE		has-purpoe	purpose		
👉 L IDENTIFICATION	initial-identifier	identified	identifier		target-identifier
👉 L LOCATION	initial-location	has-location	location	transitory-location	target-location
👉 L ADORNMENT-TARNISHMENT	initial-surface	ornament	surface		target-surface
👉 L EXCRETION	excreter	excreted		transitory-location	target-location
👉 L HITTING		hitting	hit		
👉 L INGESTION		ingested		transitory-location	ingerster
👉 L UNANCHORED-MOTION		in-motion		transitory-location	
👉 L WRAPPING-WEARING	initial-wearer	worn	wearer		target-wearer
👉 L MEANS		has-means	means		
👉 L MESSAGE	initial-content	topic	content		target-content
👉 L MODE		has-mode	mode		
👉 L NONCOMP		has-noncomp	noncomp		
👉 L PART-WHOLE	initial-whole	part	whole		target-whole
👉 L POSSESSION	initial-possessor	possessed	possessor		target-possessor
👉 L QUANTITY	initial-quantity	has-quantity	quantity		target-quantity
👉 L RANK	initial-rank	has-rank	rank		target-rank
👉 L SCENE	initial-scene	participant	scene	transitory-scene	target-scene
👉 L STATE	initial-state	has-state	state		target-state
👉 L QUALITY	initial-quality	has-quality	quality		target-quality
👉 L CLASS	initial-class	has-class	class		target-class
👉 L DESTRUCTION		destroyed			
👉 L SENDING		sent	sender		
👉 L SEQUENCE		follows	followed		
👉 L CAUSATION		result	causer		
👉 L CONDITION		has-condition	condition		
👉 L EXCEPTION		has-exception	exception		
👉 L REACTION		reaction	trigger		
👉 L RESULTATIVE		has-resultative	resultative		
👉 L SOCIAL-RELATION	initial-social-relation	has-social-relation	social-relation		target-social-relation
👉 L TIME	initial-time	has-time	time		target-time

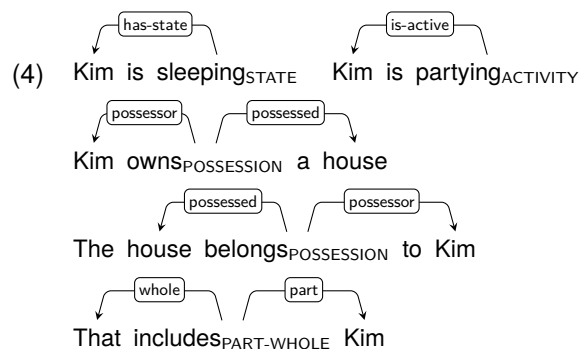
Table 1: Hierarchy of superframes and their roles

secondary predicates, etc., are added and labeled. No additional nodes are introduced.

### 3.2. Overview of the Annotation Guidelines

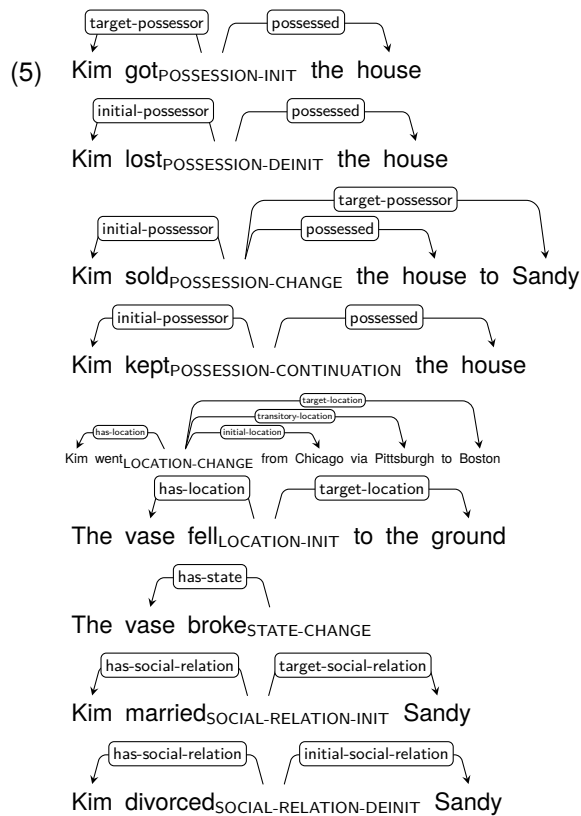
Superframes is annotated atop UD. Content words (tagged NOUN, VERB, ADJ, or ADJ in UD) receive a frame label, and dependency arcs between content words (labeled nsubj, dobj, nmod, etc.) receive a role label.

**Stative verbal predicates** An example of the annotation of some unary and binary verbal stative predicates are shown in (4). Role labels have to be drawn from the frame that the predicate is annotated with.



**Aspect** Predicates denoting events that can be framed in terms of an actual or hypothetical change of state are framed using one of the aspect operators -INIT, -DEINIT, -CHANGE, or -CONTINUATION. The second argument accord-

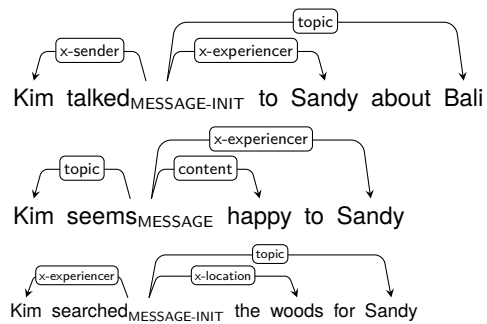
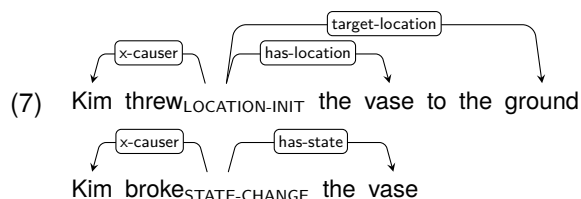
ingly receives a role label prefixed with initial-, target-, or transitory-. Examples are shown in (5).



**Mode** In addition to aspect operators, we also use the modal operators -NECESSITY, -POSSIBILITY, and -NEG. An example are shown in (6).



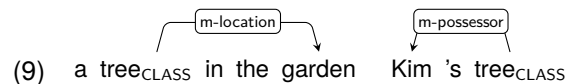
**Frame composition** Predicates can be annotated as evoking more than one frame, with a limited form of embedding. For example, a causative subject is considered to evoke an additional CAUSATION frame and fill its causer role while the core frame fills the result role. To avoid introducing an additional CAUSATION node into the annotation format, a special notation indicates this configuration, annotating the causative subject as x-causer. Analogously, arguments such as senders and perceivers are annotated with x-sender and x-experiencer, respectively. This frame composition mechanism is also used for predicate-specific arguments that do not fit into onto one of the core argument slots. Examples are shown in (7).



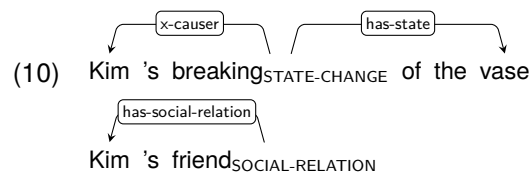
**Modification** Like non-core arguments, modifiers are assumed to evoke an additional frame and labeled with the role they fill in that frame, but with the prefix m- marking them as modifiers. Examples are shown in (8).



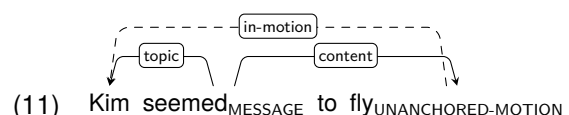
**Nonverbal predicates** We have so far shown only examples of *verbal* predicates, but everything applies to the annotation of nonverbal predicates as well. An ordinary noun like *tree* evokes the CLASS frame, marking the entity it refers to as a member of a class (in this case: the class of trees). There are no arguments here because the predicate itself doubles as a referent. However, it can be modified, as shown in (9).



Event nouns and relational nouns evoke frames and have arguments just like verbs, as shown in (10).



**Nonlocal dependencies** Many constructions introduce semantic predicate-dependent dependencies that do not correspond to (surface) syntactic dependencies. This includes constructions like control, raising, relative clauses, secondary predicates, coordination, etc. We add such links in the annotation beyond those provided by UD. Examples are shown in (11) with nonlocal dependencies dashed.



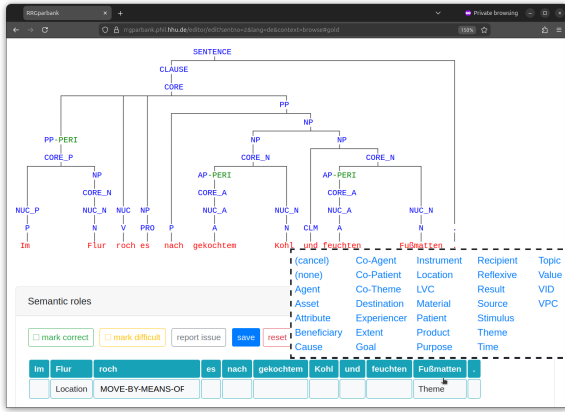


Figure 3: Browser-based VerbAtlas annotation interface showing the German translation of the sentence “The hallway smelt of boiled cabbage and old rag mats”

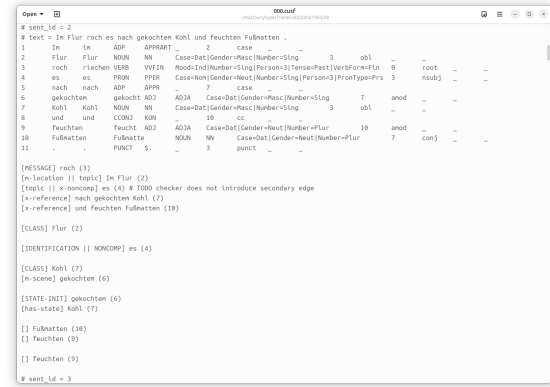
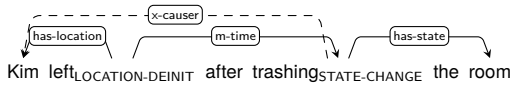


Figure 4: Text-based Superframes annotation interface. There is a UD syntax tree and 7 predicates, 5 of which have already been annotated with frames and roles.



**Figurativity and uncertainty** Figurative use of predicates is a pervasive phenomenon and often makes it hard to choose a single frame for a predicate because a more literal meaning and a more idiomatic reading are both salient. In such cases, annotators are instructed to provide annotations for both readings using labels of the form A » B where A is for the more literal reading and B is for the more figurative reading. When it is hard to choose a predicate for reasons other than figurativity, annotators can likewise provide two alternatives using the A || B notation. Examples are shown in (12).

- (12) A hush passed <sup>in-motion » scene</sup> UNANCHORED-MOTION » SCENE over the group  
 The twigs moved <sup>in-motion</sup> UNANCHORED-MOTION in the breeze <sup>m-accompanier || m-causer</sup>

## 4. Experiments

To demonstrate the viability of Superframes as an annotation scheme, we report the results of two pilot annotation projects, both carried out on a German translation of George Orwell’s novel *1984* (Orwell, 2003), one using the VerbAtlas annotation scheme and one using Superframes. Both annotation projects were carried out by paid student assistants who were either currently pursuing or had recently completed a bachelor’s degree in computational linguistics, and who were native or advanced speakers of German. Annotators worked independently but came together for weekly annotation meetings with the author, discussing difficult cases and producing consensus annotations for them.

**VerbAtlas** VerbAtlas (Di Fabio et al., 2019) is a frame inventory with full explicit coverage of the verb senses in WordNet 3.0 (Fellbaum, 1998). It contains 466 frames created by semiautomatically clustering WordNet synsets and 25 semantic role labels that are shared between frames, such as Agent, Patient, Source, Goal. Annotation was carried out between July 2021 and March 2024. Annotators were provided an annotation manual (Evang, 2024) and a graphical annotation interface that showed them syntactic trees for the sentences they had to annotate (taken from RRGparbank; Bladier et al., 2022) as well as preliminary annotations generated using InVeRo (Conia et al., 2020, 2021), which they had to correct (see Figure 3 for an example). Annotators were instructed to find the most appropriate VerbAtlas frame for each verbal predicate, considering mainly meaning correctness (the frame should map to at least one English WordNet synset whose gloss fits the use of the predicate in this context) and role coverage (the frame should have an appropriate role for every argument present in the instance). They were also instructed to make sure the role labels matched their use in the chosen frame. They were given a searchable document containing for each VerbAtlas frame 1) its VerbNet synsets with lemmas, glosses, and example sentence 2) its PropBank frames with role descriptions and annotated example sentences. No modifiers or nonverbal predicates were annotated. The same annotators annotated the corresponding parallel English sentences in parallel. Statistics of the resulting annotations are shown in Table 2.

**Superframes** The annotation was carried out between April 2024 and March 2025. Annotators were provided an annotation manual (reference anonymized) and text files that contained UD anno-

Annotator(s)		Sentences	Predicates	Arguments
jh		2 192	4 784	13 475
sg		2 405	5 122	14 799
sk		2 175	4 606	12 445
jh+sg	Both annotated Agreement	893	1 863 .74	4 669 .75
jh+sk	Both annotated Agreement	566	1 113 .76	2 466 .80
sg+sk	Both annotated Agreement	765	1 604 .71	3 548 .81

Table 2: VerbAtlas annotation results. The lower part excludes sentences with consensus annotations.

Annotator(s)		Sentences	Predicates	Dependents
ab		350	4 168	4 219
sg		296	2 955	2 431
xs		300	3 213	3 404
ab+sg	Both annotated Agreement (strict)	147	476 .71	308 .63
	Agreement (lax)		.77	.68
	Agreement (superlax)		.81	.73
ab+xs	Both annotated Agreement (strict)	150	655 .78	609 .73
	Agreement (lax)		.84	.81
	Agreement (superlax)		.89	.86
sg+xs	Both annotated Agreement (strict)	99	885 .85	869 .79
	Agreement (lax)		.92	.84
	Agreement (superlax)		.93	.86

Table 3: Superframes annotation results. The lower part excludes sentences with consensus annotations.

tations of the sentences to annotate as well as blank templates for filling in frame and role labels (see Figure 4 for an example). The templates were generated automatically from the UD annotation. Annotators were provided a Python script with which they checked their annotations for validity (all blanks filled out, all frame and role labels defined, all role labels appropriate for the respective frame, etc.) before committing them to a shared Git repository. Statistics of the resulting annotations are shown in Table 3. Strict agreement is defined as both annotators choosing the exact same label for a predicate or dependency edge. Lax agreement is also satisfied if they agree in at least one sub-label when using the uncertainty/figurativity mechanism. Superlax agreement is like lax agreement but ignores all prefixes or suffixes in labels such as -INIT, m-, or target-, focusing only on the main frame or role label.

**Close comparison** 69 sentences were doubly annotated with no consensus annotation under both schemas. We examine this intersection more closely and report overall agreement between the respective two annotators in Table 4.

**Results** Looking at the close comparison in Table 4, we see that with strict agreement, Super-

	Sentences	Predicates	Dependents
All annotated	69	98	190
VerbAtlas agreement		.67	.79
Superframes agreement (strict)		.62	.69
Superframes agreement (lax)		.71	.77
Superframes agreement (superlax)		.77	.81

Table 4: Average agreement between two annotators using VerbAtlas vs. Superframes on the same sentences. Sentences with consensus annotations are excluded.

frames scores lower than VerbAtlas for frame labels and role labels. Agreement becomes higher than for VerbAtlas with lax agreement for frames and with superlax agreement for roles. When we look at the bigger but less comparable dataset in Tables 2 and 3, we see that agreement on frame labels from .71 to .76 for VerbAtlas (depending on the pair of annotators), but from .71 to .85 for Superframes even under strict agreement. On the other hand, agreement on role labels ranges from .75 to .81 for VerbAtlas but only from .63 to .79 for Superframes under strict agreement, but from .73 to .86 under superlax agreement.

We take these numbers to hint at general viability of Superframes, but of course cannot draw very strong conclusions from them. The Superframes dataset is much smaller and the intersection of both datasets is smaller still. Annotations were made by (partially) different people and under different conditions. The number of Superframes used is much lower than that of VerbAtlas frames whereas the Superframes roles are more diverse due to VerbAtlas’s reuse of role labels across different frames. VerbAtlas focuses on verbs and their arguments whereas all content words and their relations are annotated in Superframes. Perhaps most importantly, VerbAtlas agreement profits from the anchoring bias due to pre-annotations whereas Superframes was annotated from scratch.

We provide additional statistics in Tables 5, 6, 7, 8, 9, 10, 11, and 12.

Frame	Count
IDENTIFICATION	1946
CLASS	1060
MESSAGE	973
QUALITY	778
TIME	565
MODE	538
QUANTITY	407
PART-WHOLE	353
MESSAGE-INIT	322
LOCATION	258

Table 5: Most common frame labels in the Superframes annotation

Role	Count
m-scene	725
m-quality	642
m-time	523
m-mode	500
topic	476
x-experiencer	430
m-quantity	376
has-location	344
x-sender	310
participant	261

Table 6: Most common role labels in the Superframes annotation

Pair	Count
MESSAGE MESSAGE-INIT	45
CLASS IDENTIFICATION	40
CLASS PART-WHOLE	34
IDENTIFICATION NONCOMP	28
QUALITY STATE	26

Table 7: Most common frame label disagreement pairs in the Superframes annotation

Pair	Count
m-quality m-scene	35
m-scene m-time	16
m-noncomp x-noncomp	16
m-quality m-state	14
target-content topic	13

Table 8: Most common role label disagreement pairs in the Superframes annotation

Label	Count
QUALITY » NONCOMP	41
SOCIAL-RELATION » IDENTIFICATION	40
QUALITY-NEG » QUALITY	23
COMPARISON » QUALITY	15
RANK » TIME	15

Table 9: Most common figurative frame labels in the Superframes annotation

Label	Count
SOCIAL-RELATION    STATE	8
CLASS    LOCATION	7
STATE    QUALITY	5
STATE    SOCIAL-RELATION	5
MESSAGE    SEQUENCE	4

Table 10: Most common uncertain frame labels in the Superframes annotation

VerbAtlas frame	Superframe	Count
KNOW	MESSAGE	86
SPEAK	MESSAGE-INIT	77
SEEM	MESSAGE	75
SEE	MESSAGE	73
EXIST-WITH-FEATURE	SCENE	47
WRITE	MESSAGE-INIT	38
EXIST_LIVE	EXISTENCE	37
LIE	LOCATION	33
GO-FORWARD	LOCATION-INIT	32
EXIST_LIVE	SCENE	32

Table 11: Most common combinations of VerbAtlas and Superframes frames

VerbAtlas role	Superframes role	Count
Time	m-time	392
Theme	has-location	287
Agent	x-causer	257
Experiencer	x-experiencer	241
Agent	x-sender	227
Theme	topic	224
Agent	x-experiencer	145
Destination	target-location	139
Stimulus	topic	121
Theme	content	115

Table 12: Most common combinations of VerbAtlas and Superframes roles

## 5. Conclusions, Limitations, and Future Work

We have presented Superframes, a frame-semantic annotation scheme that aims to enable consistent annotation of predicates with frame labels and dependents with role labels across languages, achieved through a small number of frames, frame composition, aspect decomposition, and annotation atop Universal Dependencies. Non-local dependencies, figurativity, idiomaticity, and uncertainty are addressed through dedicated mechanisms. We have presented the results of a preliminary annotation study where Superframes is compared with a traditional annotation scheme with a larger number of frames. We were able to show higher agreement for Superframes under certain conditions, although it should be noted that the comparability is limited, especially due to the fact that annotators corrected pre-annotations for VerbAtlas but annotated from scratch for Superframes. Based on the insights from annotation discussion, we are currently in the process of revising the scheme and making the inventory of superframes more compact and more systematic, as well as preparing a larger-scale and more systematic annotation effort.

## 6. Acknowledgements

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